

## Abstract of the Disclosure

A disturbance compensation module using learning control generates a control input to compensate for track position errors due to a periodic disturbance occurring in an optical recording medium in an optical recording medium drive servo system of an optical recording/reproducing apparatus. The module includes a first filter to filter the track position errors and a memory to store control inputs to compensate for a track control cycle in a corresponding address. A second filter filters the control inputs stored in the memory. An adder adds the filtered track position errors from the first filter to the filtered control inputs from the second filter and outputs a result to the memory, updating the control inputs to compensate for the track position errors.